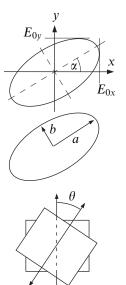
## 8.6 Polarisation

## Elliptical polarisation<sup>a</sup>

Elliptical polarisation	$\boldsymbol{E} = (E_{0x}, E_{0y} e^{\mathbf{i}\delta}) e^{\mathbf{i}\delta}$	(8.80)
Polarisation angle <sup>b</sup>	$\tan 2\alpha = \frac{2E_{0x}E_{0y}}{E_{0x}^2 - E_{0y}^2}$	$-\cos\delta$ (8.81)
Ellipticity <sup>c</sup>	$e = \frac{a - b}{a}$	(8.82)
Malus's law <sup>d</sup>	$I(\theta) = I_0 \cos^2 \theta$	(8.83)

electric field E wavevector propagation axis z angular frequency × time  $E_{0x}$  x amplitude of **E**  $E_{0v}$  y amplitude of **E** relative phase of  $E_v$ with respect to  $E_x$ polarisation angle ellipticity semi-major axis semi-minor axis  $I(\theta)$  transmitted intensity incident intensity  $I_0$ polariser-analyser angle



<sup>&</sup>lt;sup>a</sup>See the introduction (page 161) for a discussion of sign and handedness conventions.

## Jones vectors and matrices

Normalised electric field <sup>a</sup>	$\boldsymbol{E} = \begin{pmatrix} E_x \\ E_y \end{pmatrix};   \boldsymbol{E}  = 1$	(8.84)	$E$ electric field $E_x$ x component of $E$ $E_y$ y component of $E$
Example vectors:	$E_{x} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \qquad E_{45} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -\mathbf{i} \end{pmatrix} \qquad E_{1} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -\mathbf{i} \end{pmatrix}$	V - ( )	$E_{45}$ 45° to x axis $E_{\rm r}$ right-hand circular $E_{\rm l}$ left-hand circular
Jones matrix	$E_{\rm t} = \mathbf{A}E_{\rm i}$	(8.85)	$egin{array}{ll} E_{ m t} & { m transmitted vector} \\ E_{ m i} & { m incident vector} \\ { m A} & { m Jones \ matrix} \end{array}$
Example matric	es:		
Linear polariser	$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$	Linear polariser	$y = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$
Linear polariser at $45^{\circ}$ $\frac{1}{2}\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$		Linear polariser at $-45^{\circ}$ $\frac{1}{2}\begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$	
Right circular p	polariser $\frac{1}{2} \begin{pmatrix} 1 & \mathbf{i} \\ -\mathbf{i} & 1 \end{pmatrix}$	Left circular polar	riser $\frac{1}{2} \begin{pmatrix} 1 & -\mathbf{i} \\ \mathbf{i} & 1 \end{pmatrix}$
$\lambda/4$ plate (fast	$ e^{\mathbf{i}\pi/4} \begin{pmatrix} 1 & 0 \\ 0 & \mathbf{i} \end{pmatrix} $	$\lambda/4$ plate (fast $\perp x$	$e^{\mathbf{i}\pi/4} \begin{pmatrix} 1 & 0 \\ 0 & -\mathbf{i} \end{pmatrix}$

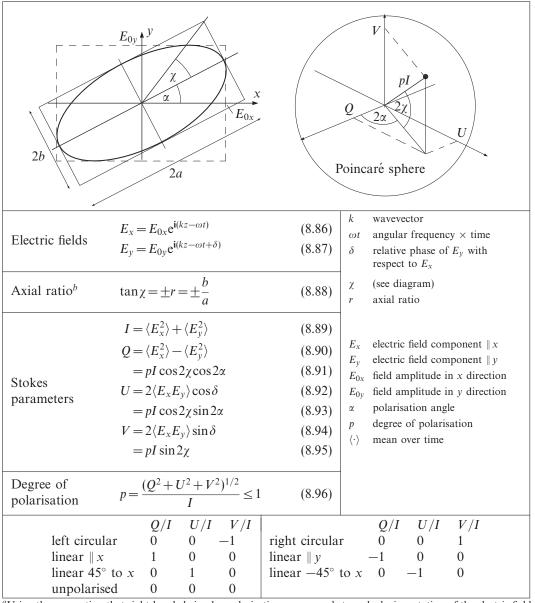
<sup>&</sup>lt;sup>a</sup>Known as the "normalised Jones vector."

<sup>&</sup>lt;sup>b</sup>Angle between ellipse major axis and x axis. Sometimes the polarisation angle is defined as  $\pi/2-\alpha$ .

<sup>&</sup>lt;sup>c</sup>This is one of several definitions for ellipticity.

<sup>&</sup>lt;sup>d</sup>Transmission through skewed polarisers for unpolarised incident light.

## Stokes parameters<sup>a</sup>



<sup>&</sup>lt;sup>a</sup>Using the convention that right-handed circular polarisation corresponds to a clockwise rotation of the electric field in a given plane when looking towards the source. The propagation direction in the diagram is out of the plane. The parameters I, Q, U, and V are sometimes denoted  $s_0$ ,  $s_1$ ,  $s_2$ , and  $s_3$ , and other nomenclatures exist. There is no generally accepted definition – often the parameters are scaled to be dimensionless, with  $s_0 = 1$ , or to represent power flux through a plane  $\bot$  the beam, i.e.,  $I = (\langle E_x^2 \rangle + \langle E_y^2 \rangle)/Z_0$  etc., where  $Z_0$  is the impedance of free space. <sup>b</sup>The axial ratio is positive for right-handed polarisation and negative for left-handed polarisation using our definitions.